## Supplementary material for the paper: Asymptotic velocities in quantum and Bohmian mechanics, by Bruno Galvan

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In this document an example is given of a relativistic trajectory space which is not asymptotically regular but nevertheless  $S_t \to S_\infty$  for  $t \to \infty$ , and it is shown that  $gS_t$ does not converge to  $gS_\infty$ , where  $gS_t := gP_t \circ \eta_t|_{g\mathbb{B}_A}^{-1}$  and  $gS_\infty(V) := S_\infty(g^{-1}V)$ .

Let us define first the trajectory

$$\mathbf{k}_{\varphi}(t) := R(\hat{\mathbf{n}}, \ln \omega t) \mathbf{v}_{\varphi} t := \mathbf{v}_{\varphi}(t) t,$$

where  $\hat{\mathbf{n}} = (0, 0, 1)$ ,  $\mathbf{v}_{\varphi} = v(\cos \varphi, \sin \varphi, 0)$ , with  $0 < v < 1/\sqrt{2}$ . By continuity we can define  $\mathbf{k}_{\varphi}(0) := 0$ . For simplicity, in this document all the trajectories will be considered as defined on  $\mathbb{R}^+$  instead of  $\mathbb{R}$ . Note that

$$\mathbf{v}_{\varphi}(t) = v(\cos(\varphi + \ln \omega t), \sin(\varphi + \ln \omega t), 0).$$

The logarithm has been introduced in order to guarantee that  $\mathbf{k}_{\varphi}$  is a world line; in fact the instantaneous velocity of  $\mathbf{k}_{\varphi}$  is

$$\mathbf{k}_{\varphi}(t) = \hat{\mathbf{n}} \wedge \mathbf{v}_{\varphi}(t) + \mathbf{v}_{\varphi}(t),$$

so that

$$\|\dot{\mathbf{k}}_{\varphi}(t)\|^{2} \leq 2\|\mathbf{v}_{\varphi}(t)\|^{2} < 1.$$

The trajectory  $\mathbf{k}_{\varphi}$  does not admit asymptotic velocity because  $\eta_t(\mathbf{k}_{\varphi}) = \mathbf{v}_{\varphi}(t)$ .

Let us consider now the trajectory space composed of the set of trajectories

$$\mathbb{B} := \{ (\mathbf{k}_{\varphi}, \mathbf{k}_{\varphi+\pi}) : \varphi \in [0, 2\pi) \}, \tag{1}$$

endowed with the measure induced by the normalized Lebesgue measure on  $[0, 2\pi)$ . The support of the measure  $S_t$  is the set

$$\eta_t(\mathbb{B}) = \{ (v \cos(\varphi + \ln \omega t), v \sin(\varphi + \ln \omega t), 0, -v \cos(\varphi + \ln \omega t), -v \sin(\varphi + \ln \omega t), 0) : : \varphi \in [0, 2\pi) \}$$

or equivalently

$$\eta_t(\mathbb{B}) = \{ (v\cos\varphi, v\sin\varphi, 0, -v\cos\varphi, -v\sin\varphi, 0) : \varphi \in [0, 2\pi) \}.$$
(2)

One can easily see that  $S_t$  is the uniform (Lebesgue) measure concentrated on  $\eta_t(\mathbb{B})$ , as in the example at the end of the section 2 of the paper. The measure  $S_t$  is therefore independent of time and  $S_t \to S_{\infty} = S_t$  for  $t \to \infty$ . Of course the support of  $S_{\infty}$  is the set (2); if g is a boost of velocity u < 1 along the x-axis, the support of  $gS_{\infty}$  is therefore the set

$$g\eta_{+}(\mathbb{B}) = \left\{ \left( \frac{v\cos\varphi - u}{1 - uv\cos\varphi}, \frac{v\sin\varphi}{\gamma(1 - uv\cos\varphi)}, 0, \frac{-v\cos\varphi - u}{1 + uv\cos\varphi}, \frac{-v\sin\varphi}{\gamma(1 + uv\cos\varphi)}, 0 \right) : \varphi \in [0, 2\pi) \right\}.$$
(3)

We will study now the support of the measure  $gS_t = gP \circ \eta_+|_{g\mathbb{B}}^{-1}$ , and we will show that, if the measure converges for  $t \to \infty$ , the support of its limit cannot be (3), and therefore  $\lim_{t\to\infty} gS_t \neq gS_{\infty}$ .

First of all let us study how does  $\mathbf{k}_{\varphi}$  transform. The graph of  $\mathbf{k}_{\varphi}$  is

$$\overline{\mathbf{k}}_{\varphi} = \{(1, v\cos(\varphi + \ln \omega t), v\sin(\varphi + \ln \omega t), 0)t : t > 0\},\$$

By defining  $\theta := \ln \omega t$  we can write

$$\overline{\mathbf{k}}_{\varphi} = \{(1, v \cos(\varphi + \theta), v \sin(\varphi + \theta), 0)e^{\theta} / \omega : \theta \in \mathbb{R}\}.$$

The transformed graph is:

$$g\overline{\mathbf{k}}_{\varphi} = \{(\gamma[1 - uv\cos(\varphi + \theta)], \gamma[v\cos(\varphi + \theta) - u], v\sin(\varphi + \theta), 0)e^{\theta}/\omega : \theta \in \mathbb{R}\}.$$

Let

$$\tilde{s}(\varphi, \theta) := \frac{e^{\theta}\gamma}{\omega} [1 - uv\cos(\varphi + \theta)].$$

Note that  $\tilde{s}(\varphi, \theta) \to 0$  for  $\theta \to -\infty$  and  $\tilde{s}(\varphi, \theta) \to \infty$  for  $\theta \to \infty$ . Note moreover that

$$\tilde{s}(\varphi, \theta + 2n\pi) = e^{2n\pi} \tilde{s}(\varphi, \theta) \text{ for } n = 1, 2, \dots$$
 (4)

The  $\theta$ -derivative of  $\tilde{s}(\varphi, \theta)$  is greater than 0:

$$\partial_{\theta}\tilde{s}(\varphi,\theta) = \frac{e^{\theta}\gamma}{\omega} [1 - uv\cos(\varphi + \theta)] + \frac{e^{\theta}\gamma}{\omega} uv\sin(\varphi + \theta) = \frac{e^{\theta}\gamma}{\omega} \{1 + uv[\sin(\varphi + \theta) - \cos(\varphi + \theta)]\} > 0$$

because  $uv < 1/\sqrt{2}$  and  $\sin \theta - \cos \theta \ge -2/\sqrt{2}$ . The function  $\tilde{s}(\varphi, \cdot)$  is therefore invertible, and let  $\tilde{\theta}(\varphi, \cdot) := \tilde{s}^{-1}(\varphi, \cdot)$ ; note that  $\tilde{\theta}(\varphi, \cdot)$  is increasing in the interval  $(0, \infty)$ , with  $\lim_{s\to 0} \tilde{\theta}(\varphi, s) = -\infty$  and  $\lim_{s\to\infty} \tilde{\theta}(\varphi, s) = \infty$ . Moreover, from the equality (4) one easily deduces the equality

$$\tilde{\theta}(\varphi, s) + 2n\pi = \tilde{\theta}(\varphi, se^{2n\pi}) \text{ for } n = 1, 2, \dots$$
 (5)

that will be utilized later. We can therefore write

$$g\overline{\mathbf{k}}_{\varphi} = \{(\gamma[1-uv\cos(\varphi+\tilde{\theta}(\varphi,s))], \gamma[v\cos(\varphi+\tilde{\theta}(\varphi,s))-u], v\sin(\varphi+\tilde{\theta}(\varphi,s)), 0)e^{\tilde{\theta}(\varphi,s)}/\omega : s > 0\}$$

Since, by definition,

$$s = \frac{e^{\theta(\varphi,s)}\gamma}{\omega} [1 - uv\cos(\varphi + \tilde{\theta}(\varphi,s))],$$

we can also write

$$g\overline{\mathbf{k}}_{\varphi} = \left\{ \left( 1, \frac{v\cos(\varphi + \tilde{\theta}(\varphi, s)) - u}{1 - uv\cos(\varphi + \tilde{\theta}(\varphi, s))}, \frac{v\sin(\varphi + \tilde{\theta}(\varphi, s))}{\gamma[1 - uv\cos(\varphi + \tilde{\theta}(\varphi, s))]}, 0 \right) s : s > 0 \right\},\$$

and therefore the transformed trajectory  $g\mathbf{k}_{\varphi}$  is

$$g\mathbf{k}_{\varphi}(s) = \left(\frac{v\cos(\varphi + \tilde{\theta}(\varphi, s)) - u}{1 - uv\cos(\varphi + \tilde{\theta}(\varphi, s))}, \frac{v\sin(\varphi + \tilde{\theta}(\varphi, s))}{\gamma[1 - uv\cos(\varphi + \tilde{\theta}(\varphi, s))]}, 0\right)s.$$

Let us study now the set  $g\mathbb{B}$ , where  $\mathbb{B}$  is defined by definition (1). We have:

$$\eta_s(g\mathbb{B}) = \Big\{ \Big( \frac{v\cos(\varphi + \tilde{\theta}(\varphi, s)) - u}{1 - uv\cos(\varphi + \tilde{\theta}(\varphi, s))}, \frac{v\sin(\varphi + \tilde{\theta}(\varphi, s))}{\gamma[1 - uv\cos(\varphi + \tilde{\theta}(\varphi, s))]}, 0, \\ \frac{-v\cos(\varphi + \tilde{\theta}(\varphi + \pi, s)) - u}{1 + uv\cos(\varphi + \tilde{\theta}(\varphi + \pi, s))}, \frac{-v\sin(\varphi + \tilde{\theta}(\varphi + \pi, s))}{\gamma[1 + uv\cos(\varphi + \tilde{\theta}(\varphi + \pi, s))]}, 0 \Big) : \varphi \in [0, 2\pi) \Big\}.$$

Now, suppose that  $\tilde{\theta}(\varphi, s_0) \neq \tilde{\theta}(\varphi + \pi, s_0)$  for some  $\varphi$  and  $s_0$ ; then the set  $\eta_{s_0}(g\mathbb{B})$ , which is the support of  $gS_{s_0}$ , is different from the set (3), which is the support of  $gS_{\infty}$ , and therefore  $gS_{s_0} \neq gS_{\infty}$ . From the equality (5) one deduces that  $\eta_{s_0}(g\mathbb{B}) = \eta_{s_n}(g\mathbb{B})$  for  $n = 1, 2, \ldots$ , where  $s_n := se^{2n\pi}$ . As a consequence if  $S_s$  converges for  $s \to \infty$  its limit cannot be  $gS_{\infty}$ .

In order to prove the thesis, we have still to prove that there exists some  $\varphi$  and  $s_0$  such that  $\tilde{\theta}(\varphi, s_0) \neq \tilde{\theta}(\varphi + \pi, s_0)$ . This is trivial: chose  $\varphi$  and  $\theta$  such that  $\varphi + \theta \neq (2n+1)\pi/2$ , and define  $s_0 := \gamma e^{\theta} [1 - uv \cos(\varphi + \theta)]$ . This implies that  $\tilde{\theta}(\varphi, s_0) = \theta$ ; suppose that  $\tilde{\theta}(\varphi, s_0) = \theta$  as well; this implies in turn that

$$\frac{\gamma e^{\theta}}{\omega} [1 - uv\cos(\varphi + \theta)] = s_0 = \frac{\gamma e^{\theta}}{\omega} [1 - uv\cos(\varphi + \pi + \theta)],$$

which is impossible if  $uv \neq 0$ .